

The Group Law on Weierstrass Elliptic Curves

An Elementary Formal Proof in Any Characteristic

David Kurniadi Angdinata¹ **Junyan Xu**²

¹London School of Geometry and Number Theory, UK

²Cancer Data Science Laboratory, National Cancer Institute, Bethesda, MD, USA

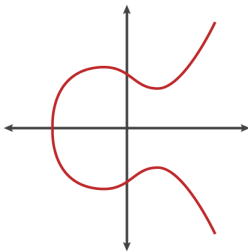
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Elliptic curves

An **elliptic curve** over a field F is a pair (E, \mathcal{O}) :

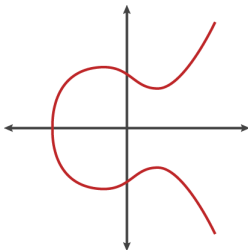
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- \mathcal{O} is a distinguished point on E defined over F



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Applications:

- computational mathematics
 - primality testing, integer factorisation, public-key cryptography
- algebraic geometry and number theory
 - Fermat's last theorem, the Birch and Swinnerton-Dyer conjecture

Weierstrass equations

Theorem (corollary of *Riemann-Roch*)

Any elliptic curve E over F can be given by $E(X, Y) = 0$, where

$$E(X, Y) := Y^2 + a_1XY + a_3Y - (X^3 + a_2X^2 + a_4X + a_6),$$

for some $a_i \in F$ such that $\Delta(a_i) \neq 0$, with \mathcal{O} the point at infinity.

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- If $\text{char}(F) \neq 2, 3$, then E has a **short Weierstrass model**

$$E(X, Y) := Y^2 - (X^3 + aX + b), \quad a, b \in F,$$

where $\Delta(a, b) = -16(4a^3 + 27b^2)$.

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- If $\text{char}(F) \neq 2$, then E has an **Edwards model**

$$E(X, Y) := X^2 + Y^2 - (1 + dX^2Y^2), \quad d \in F \setminus \{0, 1\},$$

with $\mathcal{O} := (1, 0)$.

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In the Weierstrass model, an **elliptic curve** over F is the data of:

- five coefficients $a_1, a_2, a_3, a_4, a_6 \in F$, and
- a proof that $\Delta(a_1, a_2, a_3, a_4, a_6) \neq 0$.

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```
structure weierstrass_curve (F : Type) := (a1 a2 a3 a4 a6 : F)

def weierstrass_curve.Δ {F : Type} [comm_ring F] (W : weierstrass_curve F) : F :=
  -(E.a1^2 + 4*E.a2)*(E.a1^2*E.a6 + 4*E.a2*E.a6 - E.a1*E.a3*E.a4 + E.a2*E.a3^2 - E.a4^2)
  - 8*(2*E.a4 + E.a1*E.a3)^3 - 27*(E.a3^2 + 4*E.a6)^2
  + 9*(E.a1^2 + 4*E.a2)*(2*E.a4 + E.a1*E.a3)*(E.a3^2 + 4*E.a6)

structure elliptic_curve (F : Type) [comm_ring F] extends weierstrass_curve F :=
  (Δ' : units F) (coe_Δ' : ↑Δ' = to_weierstrass_curve.Δ)
```

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In the Weierstrass model, a **point** on E is either:

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- two affine coordinates $x, y \in F$ and a proof that $(x, y) \in E$.

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```
variables {F : Type} [field F] (E : elliptic_curve F)

def polynomial : F[X][Y] :=
  Y^2 + C (C E.a1 * X + C E.a3) * Y - C (X^3 + C E.a2 * X^2 + C E.a4 * X + C E.a6)

def equation (x y : F) : Prop := (E.polynomial.eval (C y)).eval x = 0

inductive point
| zero
| some {x y : F} (h : E.equation x y)
```

Group law

Theorem (the group law)

The points of E form an abelian group under a geometric addition law.

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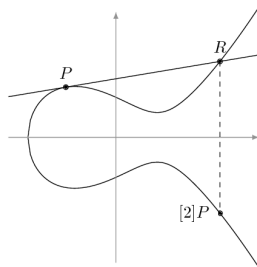
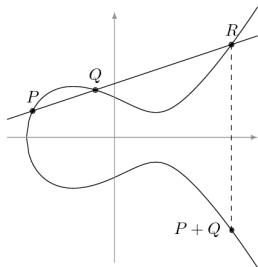
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Negation and addition are characterised by

$$P + Q + R = 0 \iff P, Q, R \text{ are collinear.}$$



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Theorem (the group law)

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Negation is given by $-(x, y) := (x, \sigma(y))$, where

$$\sigma(Y) := -Y - a_1X - a_3.$$

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def neg_polynomial : F[X][Y] := -Y - C (C E.a1 * X + C E.a3)
def neg_Y (x y : F) : F := (E.neg_polynomial.eval (C y)).eval x
lemma equation_neg {x y : F} : E.equation x y → E.equation x (E.neg_Y x y) := ...
def neg : E.point → E.point
| zero := zero
| (some h) := some (equation_neg h)
instance : has_neg E.point := ⟨neg⟩
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$$-(Y \cdot \sigma(Y)) = Y^2 + a_1XY + a_3Y$$

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Note: in the **coordinate ring** $F[E] := F[X, Y]/\langle E(X, Y) \rangle$,

$$-(Y \cdot \sigma(Y)) = Y^2 + a_1XY + a_3Y \equiv X^3 + a_2X^2 + a_4X + a_6.$$

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Addition is given by $(x_1, y_1) + (x_2, y_2) := -(x_3, y_3)$, where

$$x_3 := \lambda^2 + a_1\lambda - a_2 - x_1 - x_2,$$

$$y_3 := \lambda(x_3 - x_1) + y_1.$$

```
def add : E.point → E.point → E.point
| zero P := P
| P zero := P
| (some h1) (some h2) := some (equation_add h1 h2)

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Here,

$$\lambda := \begin{cases} \frac{y_1 - y_2}{x_1 - x_2} & x_1 \neq x_2 \\ \frac{3x_1^2 + 2a_2x_1 + a_4 - a_1y_1}{y_1 - \sigma(y_1)} & y_1 \neq \sigma(y_1) \\ \infty & \text{otherwise} \end{cases}.$$

Attempts at proof

One may attempt to prove the axioms directly.

```
instance : add_group E.point :=
{ zero      := zero,
  neg       := neg,
  add       := add,
  zero_add  := rfl,    -- by definition
  add_zero  := rfl,    -- by definition
  add_left_neg := ...,  -- by cases
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Associativity is a proof that

$$(P + Q) + R = P + (Q + R),$$

where each $+$ has five cases!

In the generic case, this is an equality of polynomials with 26,082 terms.

In contrast, the `ring` tactic in Lean can handle at most 1,000 terms.

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Proof 1: just do it.

- elementary but slow
- several known formalisations
 - Théry (Coq, 2007): short Weierstrass model $Y^2 = X^3 + aX + b$
 - Hales, Raya (Isabelle, 2020): Edwards model $X^2 + Y^2 = 1 + dX^2Y^2$
 - Fox, Gordon, Hurd (HOL4, 2006): long Weierstrass model $Y^2 + a_1XY + a_3Y = X^3 + a_2X^2 + a_4X + a_6$ but no associativity

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Proof 2: ad-hoc argument with projective geometry.

- only works generically via *Cayley-Bacharach*
- no known formalisations
 - our original attempt

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Proof 4: identify with the *degree zero Weil divisor class group* $\text{Pic}_F^0(E)$.

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Proof 5: identify with the *ideal class group* $\text{Cl}(F[E])$.

- purely algebraic and uses commutative algebra
- one known formalisation
 - our final proof (1,000 lines of Lean, 2023): long Weierstrass model

Sketch of proof

Proof of the group law.

- 1 Construct a function $E(F) \rightarrow \text{Cl}(F[E])$.
- 2 Prove that $E(F) \rightarrow \text{Cl}(F[E])$ respects addition.
- 3 Prove that $E(F) \rightarrow \text{Cl}(F[E])$ is injective. □

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Key: the coordinate ring $F[E]$ is an integral domain.

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Consider the function `point.to_class` given by

$$\begin{aligned} E(F) &\longrightarrow \text{Cl}(F[E]) \\ \mathcal{O} &\longmapsto [\langle 1 \rangle] \\ (x, y) &\longmapsto [\langle X - x, Y - y \rangle] \end{aligned} .$$

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The function `point.to_class` respects addition, since

$$\langle X - x_1, Y - y_1 \rangle \cdot \langle X - x_2, Y - y_2 \rangle \cdot \langle X - x_3, Y - \sigma(y_3) \rangle = \langle Y - \lambda(X - x_3) - y_3 \rangle.$$

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The function `point.to_class` is injective.

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Lemma (A)

If $f \in F[E]$, then $\deg(\text{Nm}(f)) \neq 1$.

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Lemma (A)

If $f \in F[E]$, then $\deg(\text{Nm}(f)) \neq 1$.

Proof of Lemma (A).

Let $f = p + qY$ for $p, q \in F[X]$. Then

$$\begin{aligned}\text{Nm}(f) &\equiv \det \begin{pmatrix} p & q \\ q(X^3 + a_2X^2 + a_4X + a_6) & p - q(a_1X + a_3) \end{pmatrix} \\ &= p^2 - pq(a_1X + a_3) - q^2(X^3 + a_2X^2 + a_4X + a_6).\end{aligned}$$

Then $\deg(\text{Nm}(f)) = \max(2 \deg(p), 2 \deg(q) + 3)$. □

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Proof of Lemma (B).

Multiplication by f has Smith normal form

$$[\cdot f] \sim \begin{pmatrix} p & 0 \\ 0 & q \end{pmatrix}, \quad p, q \in F[X].$$

- Taking determinants gives $\text{Nm}(f) = pq$.
- Taking quotients gives $F[E]/\langle f \rangle \cong F[X]/\langle p \rangle \oplus F[X]/\langle q \rangle$. □

Proof of injectivity

Theorem (Xu, 2022)

The function `point.to_class` is injective.

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Contradiction! □

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- proof works for nonsingular points of Weierstrass curves
- formalisation encouraged proof accessible to undergraduates
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- fully integrated to `mathlib` and even ported to `mathlib4`

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Thank you!