Rational points on elliptic curves in Lean Rational Points 2025

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eierstrass equations Nonsingular points Torsion subgroups Arithmetic theory

Introduction

The process of formalising mathematics is interesting for many reasons. One important reason is to ensure that a mathematical argument is sound and complete, as the standard literature may sometimes be hazy.

Alongside my PhD, I have been developing the *algebraic* foundations of elliptic curves in the Lean 4 theorem prover, mostly in joint work with **Junyan Xu** (**Heidelberg**), but with important contributions by Jinzhao Pan (Tongji), Kevin Buzzard and Andrew Yang (Imperial), Michael Stoll (Bayreuth), Peiran Wu (Leuven), Kenny Lau (unaffiliated), and others.

In my case, due to limitations of the algebraic geometry in Lean's mathematical library mathlib, we were forced to think outside the box. In the process, we could generalise existing definitions to suit our needs, and inadvertently discovered novel proofs of ancient results.



Weierstrass curves

In 2021, Buzzard formalised a *working* definition of an elliptic curve in terms of its Weierstrass model that is amenable for computation.

Definition

Weierstrass equations

A Weierstrass curve C_R over a commutative ring R with unity is a tuple $(a_1, a_2, a_3, a_4, a_6) \in R^5$. Given C_R , define

$$b_2 := a_1^2 + 4a_2, \qquad b_4 := 2a_4 + a_1a_3, \qquad b_6 := a_3^2 + 4a_6,$$

$$b_8 := a_1^2a_6 + 4a_2a_6 - a_1a_3a_4 + a_2a_3^2 - a_4^2, \qquad c_4 := b_2^2 - 24b_4,$$

$$c_6 := -b_2^3 + 36b_2b_4 - 216b_6, \qquad \Delta := -b_2^2b_8 - 8b_4^3 - 27b_6^2 + 9b_2b_4b_6.$$

If $\Delta \in R^{\times}$, then C_R is **elliptic**, and define $j := c_4^3/\Delta$.

This recovers all elliptic curves over Spec(R) when Pic(R) = 0.



Changes of variables

Any two Weierstrass equations of an elliptic curve are related by $(x,y)\mapsto (u^2x+r,u^3y+u^2sx+t)$ for some $u\in R^{\times}$ and some $r,s,t\in R$.

Definition

Weierstrass equations

A variable change is a tuple $v = (u, r, s, t) \in R^{\times} \times R^3$. Given C_R , define

$$v \cdot C_R := \left(\frac{a_1 + 2s}{u}, \frac{a_2 - sa_1 + 3r - s^2}{u^2}, \frac{a_3 + ra_1 + 2t}{u^3}, \frac{a_4 - sa_3 + 2ra_2 - (t + rs)a_1 + 3r^2 - 2st}{u^4}, \frac{a_6 + ra_4 + r^2a_2 + r^3 - ta_3 - t^2 - rta_1}{u^6}\right).$$

If $C_R' = v \cdot C_R$ for some $v \in R^{\times} \times R^3$, then C_R and C_R' are **isomorphic**.

Pan formalised Silverman's normal forms of C_R when char(R) = 2, 3, as well as a proof that C_{F^s} and C'_{F^s} are isomorphic over the separable closure F^s of a field F iff they have the same j. Recently, Lau formalised the Tate normal form of C_F when it has a point of order at least four.



Affine coordinates

For an R-algebra A, the A-points on C_R are given in affine coordinates.

Definition

An **affine** A-**point** on C_R is a tuple $(x,y) \in A^2$ that vanishes on

$$f_{C_R} := Y^2 + a_1 XY + a_3 Y - (X^3 + a_2 X^2 + a_4 X + a_6).$$

It is **nonsingular** if its two partial derivatives generate A. A **nonsingular** A-**point** on C_R is either \mathcal{O}_{C_R} or a nonsingular affine A-point on C_R .

Note that when C_R is elliptic, all A-points on C_R are nonsingular.

In this case, Stoll, Xu, and I formalised in 2024 the fact that the functor of affine points $\mathbf{AffSch}_R^{\mathrm{op}} \to \mathbf{Set}$ is representable by $\mathrm{Spec}(R[X,Y]/\langle f_{C_R}\rangle)$.

The group law

Addition on nonsingular *F*-points is given by explicit rational functions, where associativity is known to be *computationally difficult*: generic associativity involves an equality of polynomials with 26,082 terms!

Formalisation (A.-Xu, 2022)

The type of nonsingular F-points $C_F(F)$ forms an additive abelian group.

It suffices to show that the homomorphism $C_F(F) \to \text{Cl}(F[X,Y]/\langle f_{C_F}\rangle)$ mapping (x,y) to $[\langle X-x,Y-y\rangle]$ is injective. If it were not, then there are polynomials $f,g\in F[X]$ such that $\langle X-x,Y-y\rangle=\langle f+gY\rangle$. Then

$$\deg(\operatorname{Nm}(f+gY)) = \begin{cases} \max(2\deg(f), 2\deg(g) + 3) \\ \dim_F(F[X,Y]/\langle f_{C_F}, f + gY \rangle) \end{cases}$$

which is a contradiction.



Miscellaneous results

I formalised some basic results for $C_F(F)$:

- $C_F(F) \cong C'_F(F)$ as additive groups when C_F and C'_F are isomorphic
- the torsion subgroup $C_F(F)_{tors}$, including the statement of Mazur's torsion theorem, and the *n*-torsion subgroup $C_F(F)[n]$
- for a tower of finite Galois extensions L/K/F,

$$C_F(L)^{\operatorname{Gal}(L/K)} \cong C_F(K), \qquad C_F(L)[n]^{\operatorname{Gal}(L/K)} \cong C_F(K)[n]$$

Recently, Yang formalised a basic interface of singular Weierstrass curves.

Question (Yang, 2025)

Is there a clean description of $C_F(F)$ when C_F is not elliptic?

Silverman gives a complete description of C_F when F is perfect.



The *n*-torsion subgroup

In 2023, I attempted to formalise the isomorphism $C_F(F^s)[n] \cong (\mathbb{Z}/n\mathbb{Z})^2$.

Formalisation (A.-Wu-Xu, 2025?)

If C_F is elliptic and char $(F) \neq \ell$, then $T_{\ell}C_{F^s} \cong \mathbb{Z}_{\ell}^2$ as $\mathbb{Z}_{\ell}[G_F]$ -modules.

Silverman defines polynomials $\psi_n, \phi_n, \omega_n \in F^s[X, Y]$ and *claims* that there is a computational proof for the multiplication-by-n formula

$$[n](x,y) = \left(\frac{\phi_n(x)}{\psi_n^2(x)}, \frac{\omega_n(x,y)}{\psi_n^3(x,y)}\right).$$

Computing $\deg(\phi_n) = n^2$ and $\deg(\psi_n^2) = n^2 - 1$, and proving that $(\phi_n, \psi_n^2) = 1$, imply that $\# \ker[n] = n^2$, and the result follows formally.

The complete argument also recovers $T_{\ell}C_{F^s}$ when $\operatorname{char}(F)=\ell$.



Projective coordinates

Definition

The weighted projective space \mathbb{P}_R^w with weights $w = (w_0, \dots, w_n)$ is

$$\{(x_0,\ldots,x_n)\in R^{n+1}:\langle x_0,\ldots,x_n\rangle=R\}/R^{\times},$$

with an R^{\times} -action given by $u \cdot (x_0, \dots, x_n) = (u^{w_0} x_0, \dots, u^{w_n} x_n)$.

This is precisely $\operatorname{Proj} R[X_0, \dots, X_n]^w$ when $\operatorname{Pic}(R) = 0$, and the natural injection $\mathbb{P}_R^w \to \mathbb{P}_{\operatorname{Frac}(R)}^w$ is bijective when R is a discrete valuation ring.

Definition

A nonsingular Jacobian A-point on C_R is an element of $\mathbb{P}^{(2,3,1)}_A$ that vanishes in the (2,3,1)-weighted homogenisation $f_{C_R}^{(2,3,1)} \in R[X,Y,Z]$ of f_{C_R} , such that its three partial derivatives generate A.



Division polynomials

Definition

Given C_R , the *n*-th division polynomial $\psi_n \in R[X, Y]$ is given by

$$\begin{split} &\psi_0 := 0, \\ &\psi_1 := 1, \\ &\psi_2 := 2Y + a_1X + a_3, \\ &\psi_3 := 3X^4 + b_2X^3 + 3b_4X^2 + 3b_6X + b_8, \\ &\psi_4 := \psi_2 \cdot \left(2X^6 + b_2X^5 + 5b_4X^4 + 10b_6X^3 + 10b_8X^2 + (b_2b_8 - b_4b_6)X + (b_4b_8 - b_6^2)\right), \\ &\psi_{2n+1} := \psi_{n+2}\psi_n^3 - \psi_{n-1}\psi_{n+1}^3, \\ &\psi_{2n} := \frac{\psi_{n-1}^2 \psi_n \psi_{n+2} - \psi_{n-2}\psi_n \psi_{n+1}^2}{\psi_2}, \\ &\psi_{-n} := -\psi_n. \end{split}$$

Numerator polynomials

Given ψ_n , the polynomials $\phi_n, \omega_n \in R[X, Y]$ are given by

$$\phi_{\mathbf{n}} := X\psi_{\mathbf{n}}^2 - \psi_{\mathbf{n}-1}\psi_{\mathbf{n}+1}, \qquad \omega_{\mathbf{n}} := \tfrac{1}{2}(\psi_{2\mathbf{n}}/\psi_{\mathbf{n}} - \mathsf{a}_1\phi_{\mathbf{n}}\psi_{\mathbf{n}} - \mathsf{a}_3\psi_{\mathbf{n}}^3).$$

It is not obvious that $\omega_n \in R[X, Y]!$ In 2024, Xu showed that this reduces to proving that ψ_n forms an elliptic sequence: for all $n, m, r \in \mathbb{Z}$,

$$\psi_{n+m}\psi_{n-m}\psi_{r}^{2} = \psi_{n+r}\psi_{n-r}\psi_{m}^{2} - \psi_{m+r}\psi_{m-r}\psi_{n}^{2}.$$

I think this is still not directly provable. Instead, Xu proved that ψ_n forms an **elliptic net** in the sense of Stange: for all $n, m, r, s \in \mathbb{Z}$,

$$\psi_{n+m}\psi_{n-m}\psi_{r+s}\psi_{r-s} = \psi_{n+r}\psi_{n-r}\psi_{m+s}\psi_{m-s} - \psi_{m+r}\psi_{m-r}\psi_{n+s}\psi_{n-s}.$$

Later, Xu gave a complete proof of the multiplication-by-n formula.



Weierstrass equations

The local theory

I believe it is possible to formalise much of the *arithmetic* foundations of elliptic curves while the algebraic geometry in mathlib catches up.

When K is a global field, reduction modulo $\mathfrak p$ is the homomorphism

$$C_{\mathcal{K}}(\mathcal{K}) \hookrightarrow C_{\mathcal{K}}(\mathcal{K}_{\mathfrak{p}}) \stackrel{\sim}{\leftarrow} C_{\mathcal{K}}(\mathcal{O}_{\mathfrak{p}}) \twoheadrightarrow C_{\mathcal{K}}(\kappa_{\mathfrak{p}}).$$

Upon developing a theory of formal groups, it should be possible to compute torsion subgroups via the Lutz–Nagell theorem, classify reduction types, define the conductor for char($\kappa_{\mathfrak{p}}$) \neq 2, 3, prove the Néron–Ogg–Shafarevich criterion, state Szpiro's conjecture, etc.

Note that Tate's algorithm was implemented by Best, Dahmen, and Huriot-Tattegrain in 2023 before elliptic curves existed in Lean 4!



Nonsingular points Torsion subgroups Arithmetic theory

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The global theory

Much of the theory over a global field K now becomes accessible!

- Isogenies can be defined in terms of their standard form when $char(F) \neq 2, 3$, which opens the door to formalising basic facts about $Hom_F(C_F, C_F')$, $End_F(C_F)$, and $Aut_F(C_F)$.
- The ℓ -adic representations $G_K \to \operatorname{Aut}(T_\ell C_{K^s})$ can be glued together to give an adelic representation $G_K \to \operatorname{GL}_2(\widehat{\mathbb{Z}})$.
- Assuming modularity, the L-function and the Tamagawa number can both be defined as products of local factors.
- In 2022, I formalised a skeleton of the full Mordell–Weil theorem over $\mathbb Q$ in Lean 3 via complete 2-descent, including explicit Galois cohomology and naïve heights. Formalising this properly in Lean 4 naturally leads to the definitions of $\mathrm{III}(C_K)$, $\mathrm{rk}(C_K)$, and $\mathrm{Reg}(C_K)$.

All of these are part of the Birch and Swinnerton-Dyer conjecture!



13 / 14

The Birch and Swinnerton-Dyer conjecture

Here is my blueprint for the Birch and Swinnerton-Dyer conjecture.

